

# Initialization in Java



Every Ice-based application needs to initialize the Ice run time, and this initialization returns a `com.zeroc.Ice.Communicator` object.

A `Communicator` is a local Java object that represents an instance of the Ice run time. Most Ice-based applications create and use a single `Communicator` object, although it is possible and occasionally desirable to have multiple `Communicator` objects in the same application.

You initialize the Ice run time by calling `com.zeroc.Ice.Util.initialize`, for example:

## Java

```
public static void main(String[] args)
{
    com.zeroc.Ice.Communicator communicator = com.zeroc.Ice.Util.initialize(args);
    ...
}
```

`Util.initialize` accepts the argument vector that is passed to `main` by the operating system. The method scans the argument vector for any [command-line options](#) that are relevant to the Ice run time. If anything goes wrong during initialization, `Util.initialize` throws an exception.



The semantics of Java arrays prevents this simple `Util.initialize` from modifying the argument vector. You can use [another overload](#) of `Util.initialize` to receive an argument vector with all Ice-related arguments removed.

Before leaving your `main` method, you must call `Communicator.destroy`. The `destroy` method is responsible for finalizing the Ice run time. In particular, in an Ice server, `destroy` waits for any operation implementations that are still executing to complete. In addition, `destroy` ensures that any outstanding threads are joined with and reclaims a number of operating system resources, such as file descriptors and memory. Never allow your `main` method to terminate without calling `destroy` first.

The general shape of our `main` method becomes:

## Java

```
public class App
{
    public static void main(String[] args)
    {
        int status = 0;
        com.zeroc.Ice.Communicator communicator = null;
        try
        {
            // correct but suboptimal, see below
            communicator = com.zeroc.Ice.Util.initialize(args);
            // ...
        }
        catch(Exception e)
        {
            e.printStackTrace();
            status = 1;
        }
        if(communicator != null)
        {
            // correct but suboptimal, see below
            communicator.destroy();
        }
        System.exit(status);
    }
}
```

This code is a little bit clunky, as we need to make sure the communicator gets destroyed in all paths, including when an exception is thrown.

Fortunately, the `Communicator` interface implements [java.lang.AutoCloseable](#): this allows us to call `initialize` in a try-with-resources statement, which closes (destroys) the communicator automatically, without an explicit call to the `destroy` method.

The preferred way to initialize the Ice run time in Java is therefore:

#### Java

```
public class App
{
    public static void main(String[] args)
    {
        int status = 0;
        try(com.zeroc.Ice.Communicator communicator = com.zeroc.Ice.Util.initialize(args))
        {
            // ...
        } // communicator is destroyed automatically here
        System.exit(status);
    }
}
```

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